

	Type	L #	Hits	Search Text	DBs	Time Stamp
1	IS&R	L1	1	("5831619").PN.	USPAT; EPO; JPO; USOCR	2004/09/03 13:15
2	BRS	L2	1	5831619.pn.	USPAT; EPO; JPO; USOCR	2004/09/03 13:15
3	BRS	L3	1	2 and circle	USPAT; EPO; JPO; USOCR	2004/09/03 13:17
4	BRS	L4	1	3 and ellipses	USPAT; EPO; JPO; USOCR	2004/09/03 14:39
5	BRS	L5	0	4 and concentric near3 circles	USPAT; EPO; JPO; USOCR	2004/09/03 14:17
6	BRS	L6	1	4 and(plurality or plural)with circle	USPAT; EPO; JPO; USOCR	2004/09/03 13:20
7	BRS	L7	0	6 and(plurality or plural)with angles	USPAT; EPO; JPO; USOCR	2004/09/03 13:20
8	BRS	L8	1	6 and(plurality or plural)and angles	USPAT; EPO; JPO; USOCR	2004/09/03 14:26
9	BRS	L9	1	8 and(plurality or plural)and radiuses	USPAT; EPO; JPO; USOCR	2004/09/03 14:25
10	BRS	L10	0	9 and project\$3	USPAT; EPO; JPO; USOCR	2004/09/03 13:22

	Type	L #	Hits	Search Text	DBs	Time Stamp
11	BRS	L11	1	9 and trac\$3	USPAT; EPO; JPO; USOCR	2004/09/03 14:06
12	BRS	L13	0	11 and (ccd or camera or sensors)with calibrat\$3	USPAT; EPO; JPO; USOCR	2004/09/03 13:24
13	BRS	L14	0	11 and (ccd or camera or sensors)and calibrat\$3	USPAT; EPO; JPO; USOCR	2004/09/03 14:28
14	BRS	L15	0	11 and calibrat\$3	USPAT; EPO; JPO; USOCR	2004/09/03 13:24
15	BRS	L16	0	12 and focal near3 length	USPAT; EPO; JPO; USOCR	2004/09/03 13:25
16	BRS	L17	0	12 and focal	USPAT; EPO; JPO; USOCR	2004/09/03 13:25
17	BRS	L12	1	11 and (ccd or camera or sensors)	USPAT; EPO; JPO; USOCR	2004/09/03 13:41
18	BRS	L18	0	12 and algorithm	USPAT; EPO; JPO; USOCR	2004/09/03 14:06
19	BRS	L19	1	6750860.pn.	USPAT; EPO; JPO; USOCR	2004/09/03 14:06
20	BRS	L20	1	19 and trac\$3	USPAT; EPO; JPO; USOCR	2004/09/03 14:06

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21	BRS	L21	1	20 and algorithm	USPAT; EPO; JPO; USOCR	2004/09/03 14:26
22	BRS	L22	0	21 and algorithm with concentric near3 circle	USPAT; EPO; JPO; USOCR	2004/09/03 14:17
23	BRS	L23	62	calculat\$3 and central near3 points and project\$3 and concentric near3 circles and algorithm	USPAT; EPO; JPO; USOCR	2004/09/03 14:19
24	BRS	L24	60	23 and project\$3 and(plurality or plural)and concentric near3 circle	USPAT; EPO; JPO; USOCR	2004/09/03 14:21
25	BRS	L25	56	24 and plane	USPAT; EPO; JPO; USOCR	2004/09/03 14:22
26	BRS	L26	52	25 and(plurality or plural)and radiuses	USPAT; EPO; JPO; USOCR	2004/09/03 14:37
27	BRS	L27	440042	"52" and(plurality or plural)and angles	USPAT; EPO; JPO; USOCR	2004/09/03 14:26
28	BRS	L28	52	26 and(plurality or plural)and angles	USPAT; EPO; JPO; USOCR	2004/09/03 14:37
29	BRS	L30	45	29 and @ad<20010402	USPAT; EPO; JPO; USOCR	2004/09/03 14:34
30	BRS	L31	41	30 and (ccd or camera or sensors)and calibrat\$3	USPAT; EPO; JPO; USOCR	2004/09/03 14:28

	Type	L #	Hits	Search Text	DBs	Time Stamp
31	BRS	L29	52	28 and calculat\$3 and central near3 points and algorithm	USPAT; EPO; JPO; USOCR	2004/09/03 14:29
32	BRS	L32	45	29 and @ad<20010402	USPAT; EPO; JPO; USOCR	2004/09/03 14:35
33	BRS	L33	7	32 and (3D or three adj dimensional)	USPAT; EPO; JPO; USOCR	2004/09/03 14:35
34	BRS	L34	7	33 and(plurality or plural)and radiuses	USPAT; EPO; JPO; USOCR	2004/09/03 14:37
35	BRS	L35	7	34 and(plurality or plural)and angles	USPAT; EPO; JPO; USOCR	2004/09/03 14:40
36	BRS	L36	4	35 and ellipses	USPAT; EPO; JPO; USOCR	2004/09/03 14:39
37	BRS	L37	7	34 and(plurality or plural)and angles	USPAT; EPO; JPO; USOCR	2004/09/03 14:40